

Lecture 10: Beyond Normal Operators

Ashwin Joy

Department of Physics, IIT Madras, Chennai - 600036

Diagonalization

- Normal operators ($\mathbf{A}\mathbf{A}^\dagger = \mathbf{A}^\dagger\mathbf{A}$) are unitarily diagonalizable
- What can we say about other operators?

Theorem

An operator \mathbf{A} is diagonalizable if there exists an \mathbf{S} , such that

$$\mathbf{S}^{-1}\mathbf{A}\mathbf{S} = \mathbf{A}_D = \begin{bmatrix} \lambda_1 & 0 & \dots \\ 0 & \lambda_2 & \dots \\ \vdots & \vdots & \ddots \end{bmatrix}$$

where the similarity operator \mathbf{S} is set up using the eigenkets of \mathbf{A}

In what follows, we prove this!

Basis Transformation

Consider \mathbf{A} in the standard basis, $\mathbb{B} = \{|e_1\rangle, |e_2\rangle, \dots, |e_N\rangle\}$

If there exists an eigenbasis of \mathbf{A} , $\mathbb{V} = \{|v_1\rangle, |v_2\rangle, \dots, |v_N\rangle\}$

We can construct the transformation operator \mathbf{S} ,

$$|v_j\rangle = \sum_k \mathbf{S}_{kj} |e_k\rangle \quad \text{with} \quad |e_k\rangle = \sum_l \mathbf{S}_{lk}^{-1} |v_l\rangle$$

$$\text{or, } \langle e_l | v_j \rangle = \mathbf{S}_{lj} \quad \dots \mathbb{B} \text{ is orthonormal}$$

Therefore,

$$\mathbf{S} = \begin{bmatrix} \langle e_1 | v_1 \rangle & \langle e_1 | v_2 \rangle & \dots \\ \langle e_2 | v_1 \rangle & \langle e_2 | v_2 \rangle & \dots \\ \vdots & \vdots & \ddots \end{bmatrix} = \underbrace{\begin{bmatrix} \vdots & \vdots & \dots \\ |v_1\rangle & |v_2\rangle & \dots \\ \vdots & \vdots & \dots \end{bmatrix}}_{\text{eigenkets as columns}}$$

Proof by Geometry

$$\begin{aligned} \mathbf{A}\mathbf{S} &= \begin{bmatrix} \mathbf{A}_{11} & \mathbf{A}_{12} & \dots \\ \mathbf{A}_{21} & \mathbf{A}_{22} & \dots \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} \vdots & \vdots & \\ |v_1\rangle & |v_2\rangle & \dots \\ \vdots & \vdots & \end{bmatrix} \\ &= \begin{bmatrix} \vdots & \vdots & \\ \lambda_1 |v_1\rangle & \lambda_2 |v_2\rangle & \dots \\ \vdots & \vdots & \end{bmatrix} \\ &= \underbrace{\begin{bmatrix} \vdots & \vdots & \\ |v_1\rangle & |v_2\rangle & \dots \\ \vdots & \vdots & \end{bmatrix}}_{\mathbf{S}} \underbrace{\begin{bmatrix} \lambda_1 & 0 & \dots \\ 0 & \lambda_2 & \dots \\ \vdots & \vdots & \ddots \end{bmatrix}}_{\mathbf{A}_D} \end{aligned}$$

Therefore,

$$\boxed{\mathbf{S}^{-1}\mathbf{A}\mathbf{S} = \mathbf{A}_D}$$

Proof by Dirac Formalism

$$\begin{aligned}(\mathbf{AS})_{ij} &= \sum_l \mathbf{A}_{il} \mathbf{S}_{lj} \\ &= \sum_l \langle e_l | \mathbf{A} | e_l \rangle \langle e_l | v_j \rangle \\ &= \langle e_i | \mathbf{A} | v_j \rangle \quad \dots \text{closure of } \mathbb{B} \\ &= \langle e_i | v_j \rangle \lambda_j \quad \dots \mathbf{A} | v_j \rangle = \lambda_j | v_j \rangle \\ &= \mathbf{S}_{ij} \lambda_j \\ &= \sum_k \mathbf{S}_{ik} \delta_{kj} \lambda_k \\ &= \sum_k \mathbf{S}_{ik} \mathbf{A}_{Dkj} \\ &= (\mathbf{SA}_D)_{ij}\end{aligned}$$

yielding,

$$\mathbf{AS} = \mathbf{SA}_D \implies \boxed{\mathbf{S}^{-1} \mathbf{AS} = \mathbf{A}_D}$$

Simultaneous Diagonalization

For some \mathbf{A} and \mathbf{B} , there exists a similarity operator \mathbf{S} , such that

$$\mathbf{S}^{-1}\mathbf{A}\mathbf{S} = \mathbf{A}_D \quad \text{and} \quad \mathbf{S}^{-1}\mathbf{B}\mathbf{S} = \mathbf{B}_D$$

if and only if, $[\mathbf{A}, \mathbf{B}] = 0$

Proof

Left as exercise, as it is similar to the case of Hermitian operators

Problem

Q. Consider the following operator in the standard basis

$$\mathbf{A} = \begin{bmatrix} 1 & 1 \\ 0 & 0.5 \end{bmatrix}$$

Compute the following

1. $\text{Tr}(e^{\mathbf{A}})$
2. $\det(e^{\mathbf{A}})$
3. \mathbf{A}^{∞}

Solution

From the characteristic equation of \mathbf{A} ,

$$0 = \det(\mathbf{A} - a\mathbf{I}) = (1 - a)(0.5 - a)$$

we get the eigenvalues, $a = 1, 0.5$

Eigenkets

$$\begin{bmatrix} 0 \\ 0 \end{bmatrix} = \underbrace{\begin{bmatrix} 0 & 1 \\ 0 & -0.5 \end{bmatrix}}_{\mathbf{A}-I} \underbrace{\begin{bmatrix} x \\ y \end{bmatrix}}_{|v\rangle} = \begin{bmatrix} y \\ -0.5y \end{bmatrix}, \quad \text{yielding } x = \text{arbitrary}, y = 0$$

We pick a normalized ket, $|v_1\rangle = [1 \ 0]^T$

$$\begin{bmatrix} 0 \\ 0 \end{bmatrix} = \underbrace{\begin{bmatrix} 0.5 & 1 \\ 0 & 0 \end{bmatrix}}_{\mathbf{A}-0.5I} \underbrace{\begin{bmatrix} x \\ y \end{bmatrix}}_{|v\rangle} = \begin{bmatrix} 0.5x + y \\ 0 \end{bmatrix}, \quad \text{yielding } x = -2y$$

We pick a normalized ket, $|v_2\rangle = [-2/\sqrt{5} \ 1/\sqrt{5}]^T$

Diagonalize A

Since $|v_1\rangle$ and $|v_2\rangle$ are linearly independent, we have

$$\mathbf{S}^{-1}\mathbf{A}\mathbf{S} = \mathbf{A}_D = \begin{bmatrix} 1 & 0 \\ 0 & 0.5 \end{bmatrix}$$

where

$$\mathbf{S} = \begin{bmatrix} 1 & -2/\sqrt{5} \\ 0 & 1/\sqrt{5} \end{bmatrix} \text{ yielding, } \mathbf{S}^{-1} = \begin{bmatrix} 1 & 2 \\ 0 & \sqrt{5} \end{bmatrix}$$

Exponentiation to an arbitrary integer ($n > 0$) is super easy!

$$\mathbf{A}^n = (\mathbf{S}\mathbf{A}_D\mathbf{S}^{-1})^n = \mathbf{S}\mathbf{A}_D^n\mathbf{S}^{-1} = \mathbf{S} \begin{bmatrix} 1 & 0 \\ 0 & 0.5^n \end{bmatrix} \mathbf{S}^{-1}$$

Therefore,

$$\lim_{n \rightarrow \infty} \mathbf{A}^n = \mathbf{S} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \mathbf{S}^{-1} = \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix}$$

Functions \mathbf{A}

For a function of \mathbf{A} , say

$$e^{\mathbf{A}} = e^{\mathbf{S}\mathbf{A}_D\mathbf{S}^{-1}} = \mathbf{S}e^{\mathbf{A}_D}\mathbf{S}^{-1} = \mathbf{S} \begin{bmatrix} e & 0 \\ 0 & \sqrt{e} \end{bmatrix} \mathbf{S}^{-1}$$

By the cyclicity of trace,

$$\boxed{\text{Tr}(e^{\mathbf{A}}) = e + \sqrt{e}}$$

By the distributivity of determinant,

$$\boxed{\det(e^{\mathbf{A}}) = e^{3/2}}$$