

Fundamentals: Measurement (Projection, POVM)
 Uncertainty Principle, Density Operator

(1) Dynamics: Evolution of $|\psi\rangle$ is described by a unitary operator.

$$|\psi(t)\rangle = U(t, 0) |\psi(0)\rangle$$

(2) Measurement: Projective, POVMs

(2a) Projective Measurement M : associated with a set of projection operators $\{P_i^{M_j}\}$ such that $\sum_i P_i = I$.

• Measuring M on $|\psi\rangle \rightarrow \frac{P_i |\psi\rangle \langle \psi| P_i}{\text{Tr}(P_i |\psi\rangle \langle \psi|)}$ with prob. $p(i)$

$$p(i) = |\langle \psi | m_i \rangle|^2 = \text{Tr}(|\psi\rangle \langle \psi| |m_i\rangle \langle m_i|) \\ = \text{Tr}(|\psi\rangle \langle \psi| P_i)$$

NOTE: Trace w/ the Dirac notation: -

$$\text{Tr}(|\psi\rangle \langle \psi| P_i) = \sum_i \langle e_i | (|\psi\rangle \langle \psi| P_i) | e_i \rangle$$

(where $\{|e_i\rangle\}$ is an ON basis for \mathcal{H})

$$\therefore \text{Tr}(|\psi\rangle \langle \psi| P_i) = \sum_i \langle e_i | \psi \rangle \langle \psi | P_i | e_i \rangle$$

$$= \sum_i \langle \psi | P_i | e_i \rangle \langle e_i | \psi \rangle$$

$$= \langle \psi | P_i | \psi \rangle \left(\text{since } \sum_i |e_i\rangle \langle e_i| = I \right)$$

$$= |\langle \psi | m_i \rangle|^2 \quad \text{QED!}$$

- M is self-adjoint $\Rightarrow M = \sum_i m_i |m_i\rangle\langle m_i|$
 $= \sum_i m_i P_i$

- Measurement transformation:-

$$|\psi\rangle\langle\psi| \longrightarrow \sum_i P_i |\psi\rangle\langle\psi| P_i = \rho$$

- Post-measurement state:

$$\text{Ensemble } \rho \equiv \{p(i), |m_i\rangle\langle m_i|\}$$

• Density operator:
 Mixture, not a superposition!

- Expectation value: $\langle M \rangle_{|\psi\rangle} = \langle \psi | M | \psi \rangle$

$$\begin{aligned} \mathbb{E}_{|\psi\rangle}(M) &= \sum_i p(i) m_i = \sum_i |\langle \psi | m_i \rangle|^2 m_i \\ &= \langle \psi | \left(\sum_i m_i |m_i\rangle\langle m_i| \right) | \psi \rangle = \langle \psi | M | \psi \rangle \end{aligned}$$

Example: Measuring σ_x on state $|\psi\rangle = \alpha_0 |0\rangle + \alpha_1 |1\rangle$

$$\sigma_x \text{ has eigenstates } |+\rangle = \frac{|0\rangle + |1\rangle}{\sqrt{2}}, |-\rangle = \frac{|0\rangle - |1\rangle}{\sqrt{2}}$$

$$P_+ = |+\rangle\langle +|, P_- = |-\rangle\langle -|$$

$$\therefore p(+)= |\langle \psi | + \rangle|^2 = \text{Tr} \left[(|\psi\rangle\langle\psi|) (|+\rangle\langle +|) \right]$$

$$\left. \begin{aligned} p(+)= \frac{|\alpha_0 + \alpha_1|^2}{2} \\ p(-)= \frac{|\alpha_0 - \alpha_1|^2}{2} \end{aligned} \right\} p(+)+p(-)=1$$

- Post-measurement state: $\rho = p(+)|+\rangle\langle +|$

(Note: $\text{Tr}(\rho) = 1$)

$$+ p(-)|-\rangle\langle -|$$

- Expectation value: $\langle \sigma_x \rangle_{|\psi\rangle} = \alpha_0^* \alpha_1 + \alpha_1^* \alpha_0$

$$\langle \Delta \sigma_x \rangle_{|\psi\rangle} = \langle \sigma_x^2 \rangle_{|\psi\rangle} - \langle \sigma_x \rangle_{|\psi\rangle}^2 = 1 - \langle \sigma_x \rangle_{|\psi\rangle}^2$$

(2b) Povm: Positive operator valued measure

$$M = \{M_i\}, \quad 0 < M_i < I, \quad \sum_i M_i = I$$

* Prob of outcome 'i': $p(i) = \langle \psi | M_i | \psi \rangle$

Correspondingly, $|\psi\rangle \rightarrow \sqrt{M_i} |\psi\rangle$

Post-measurement state: $\sum_i \sqrt{M_i} |\psi\rangle \langle \psi| \sqrt{M_i}$

Eg: Task: To distinguish between $|0\rangle$ and $|+\rangle$

Povm with elements: $M_1 = \frac{\sqrt{2}}{1+\sqrt{2}} |1\rangle\langle 1|$

$$M_1 + M_2 = |1\rangle\langle 1| + |-\rangle\langle -|$$

$$= \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{3}{2} \end{pmatrix}$$

Has e-values $1 \pm \sqrt{2}$

$\Rightarrow M_1 + M_2 > I$!

$$M_2 = \frac{\sqrt{2}}{1+\sqrt{2}} (|-\rangle\langle -|)$$

$$M_3 = I - M_1 - M_2$$

\Rightarrow Zero-error discrimination strategy:

If system is in state $|0\rangle$, outcome '1' (M_1) cannot occur!

$|-\rangle$, outcome '2' (M_2) cannot occur!

i.e. in state $|0\rangle$, $p(1) = 0$

$|-\rangle$, $p(2) = 0$

i.e. if M_1 is realized, system is in state $|-\rangle$

M_2 " " " state $|0\rangle$

M_3 " \rightarrow no information about the state of the system!

(3) Non-orthogonal quantum states cannot be distinguished perfectly.

* 2-party game: A $\xrightarrow{\quad\quad\quad}$ B
 $\{|\psi_1\rangle, |\psi_2\rangle, \dots, |\psi_N\rangle\}$

A sends $|\psi_i\rangle$ ($1 \leq i \leq N$); can B identify 'i'?

(a) If $\{|\psi_i\rangle\}$ are mutually orthogonal,

B performs the measurement: $M_i = |\psi_i\rangle\langle\psi_i|$
($1 \leq i \leq N$)

For completeness: $M_{N+1} = I - \sum_i |\psi_i\rangle\langle\psi_i|$

(b) If $|\psi_1\rangle, |\psi_2\rangle$ are non-orthogonal:-

* Suppose \exists a measurement M with operators $\{M_1, M_2\}$

such that $\langle\psi_1|M_1|\psi_1\rangle = 1$; $\langle\psi_2|M_2|\psi_2\rangle = 1$ — (*)

$$\sum_i M_i = I \Rightarrow \langle\psi_1|M_2|\psi_1\rangle = 0$$

$$\Rightarrow \sqrt{M_2}|\psi_1\rangle = 0$$

Let $|\psi_2\rangle = \alpha|\psi_1\rangle + \beta|\psi_1^\perp\rangle$; $|\alpha|^2 + |\beta|^2 = 1$

$$\therefore \sqrt{M_2}|\psi_2\rangle = \beta \sqrt{M_2}|\psi_1^\perp\rangle$$

$$\Rightarrow \langle\psi_2|M_2|\psi_2\rangle = |\beta|^2 \langle\psi_1^\perp|M_2|\psi_1^\perp\rangle$$

$$\leq |\beta|^2 < 1$$

in contradiction with (*) ($\langle\psi_2|M_2|\psi_2\rangle = 1$!)

QED.

(4) Uncertainty Principle:-

$$\text{Standard deviation: } (\Delta M)_\psi^2 = \langle (M - \langle M \rangle)^2 \rangle$$

$$= \langle M^2 \rangle_\psi - \langle M \rangle_\psi^2$$

$$= \langle \psi | M^2 | \psi \rangle - (\langle \psi | M | \psi \rangle)^2.$$

For any pair of observables A, B ,

$$(\Delta A)_\psi (\Delta B)_\psi \geq \frac{|\langle \psi | [A, B] | \psi \rangle|}{2}$$

x ——— x ——— x ——— x